

A discussion of WIND Profilers

- Lehmann et al. WMO/WIGOS workshop; 201:
https://www.wmo.int/pages/prog/www/IMOP/meetings/SI/LangenWorkshop/Langen_Doc_Plan.html
- *I use heavily from Dan Wolfe and Steve Cohen [AMS Short Course on the Fundamentals of Boundary Layer Wind and Temperature Profiling using: Radar and Acoustic Techniques, 8-9 February 2003, Long Beach, California*
- <https://psl.noaa.gov/data/obs/instruments/WindProfilerDescription.html><https://psl.noaa.gov/data/obs/instruments/WindProfilerDescription.html>

WIND how is it measured?

The WMO Integrated Global Observing System (WIGOS)



From WMO WIGOS-Flyer: http://www.wmo.int/pages/prog/www/wigos/index_en.html

Vertical profiles of wind vector:

Ground based:

- Radiosondes
- Pilot-Balloons
- Aircraft
- Wind profilers
- (Weather radars)

Space based:

- AMV's
- Indirect (through mass field)

We will discuss radars

WIND Profilers: Basics (clear air)

Refractive Index - n: $(n - 1)_{Air} = \frac{k_1 p}{z_a T} + \frac{k_2 e}{z_w T} + \frac{k_3 e}{z_w T^2}$ or Using $\rightarrow N = (n - 1) \cdot 10^6$

$$N = 77.6 \frac{p}{T} + 71.6 \frac{e}{T} + 3.7 \cdot 10^5 \frac{e}{T^2}$$

<https://angeo.copernicus.org/articles/34/767/2016/angeo-34-767-2016.pdf>

$$C_n^2 = \frac{\langle [n(r + \delta) - n(r)]^2 \rangle}{|\delta|^{2/3}}$$

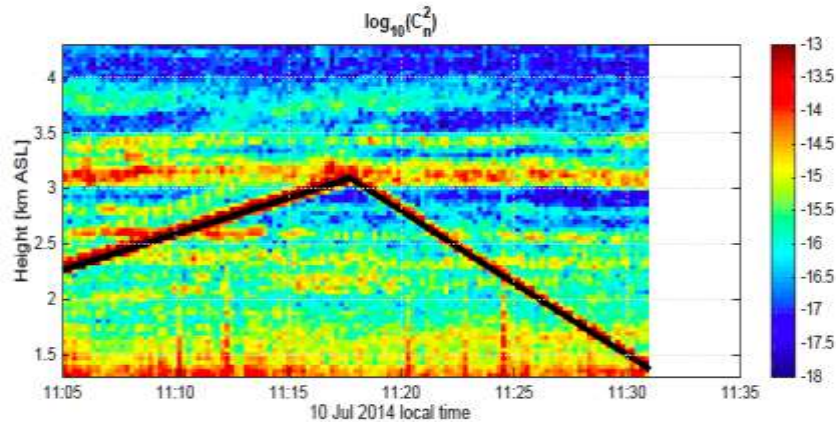
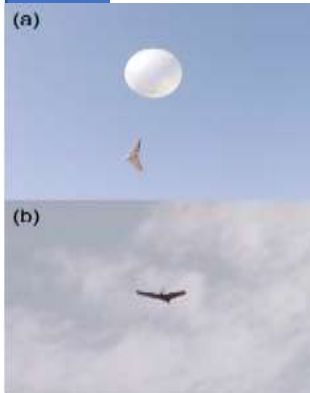
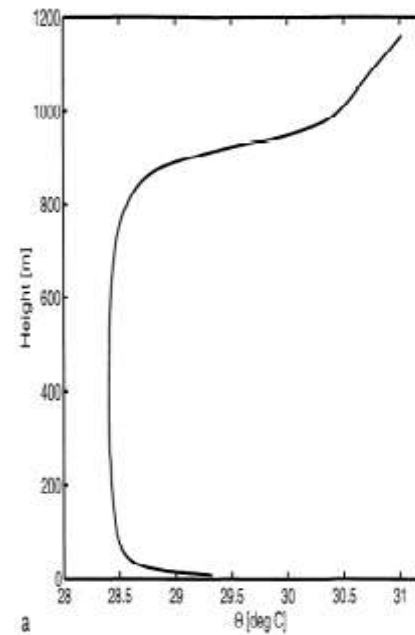
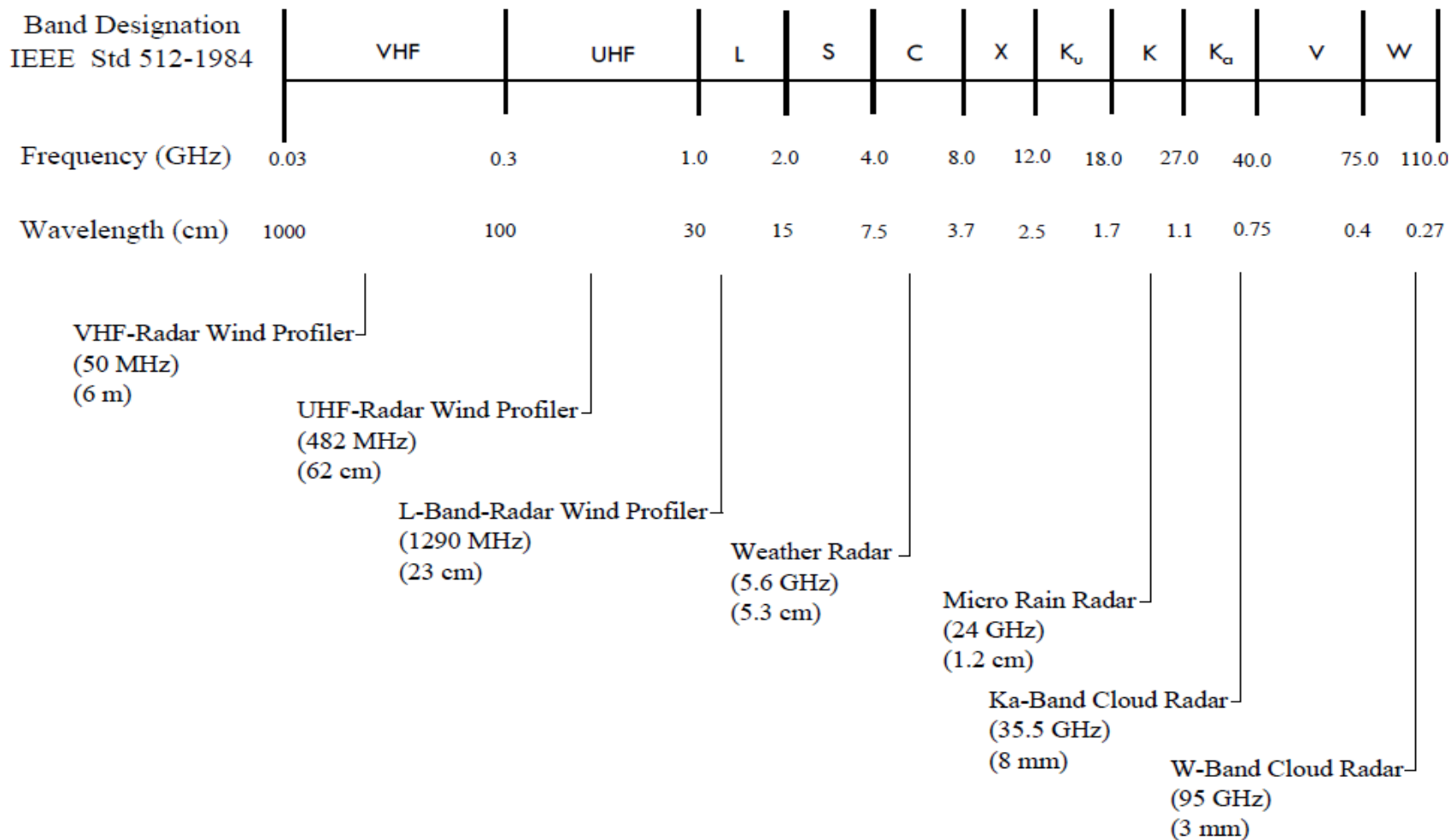


Figure 5. The black line represents the DataHawk altitude as a function of time plotted on top of the calibrated range-corrected received power for the morning flight (11:05–11:30). The DataHawk was dropped by a tethered balloon at an approximate altitude of 2.25 km. In this case, there is an ascent from its initial altitude to 3 km, followed by a descent over SOUSY down to 1.5 km.

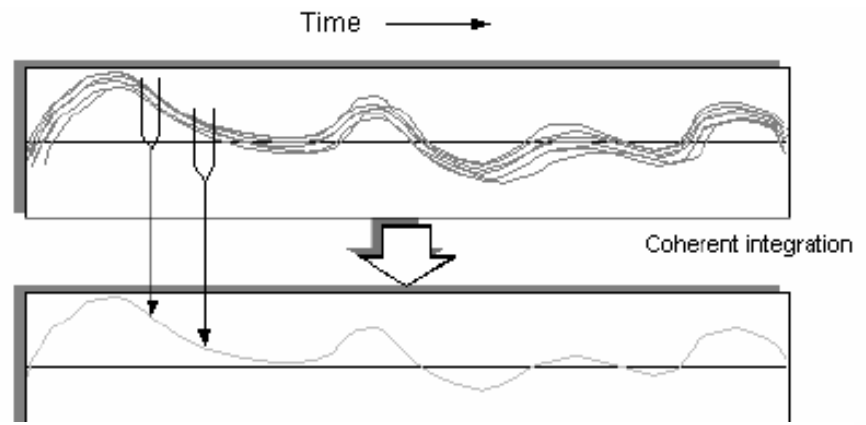
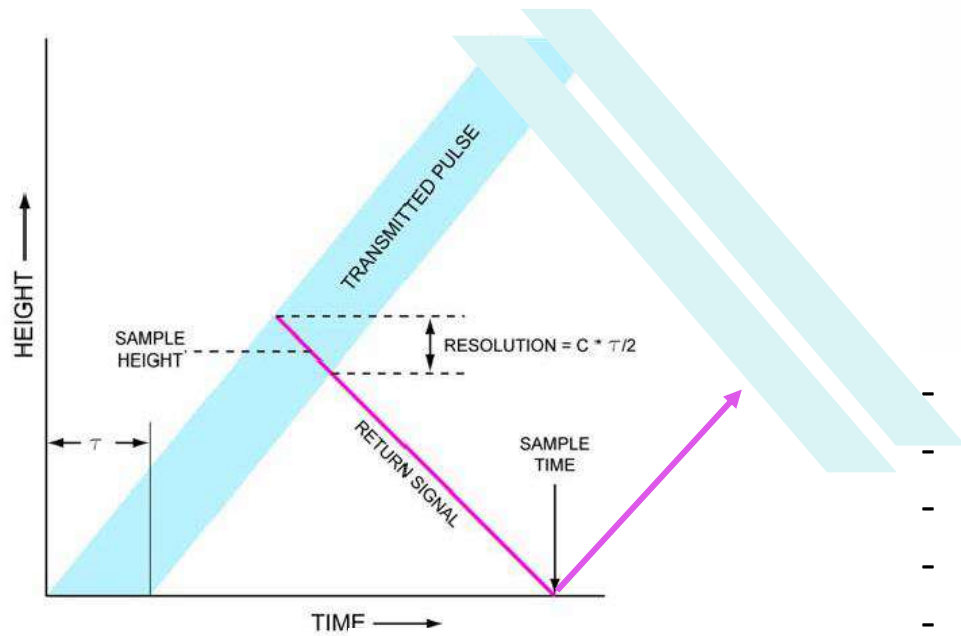
WIND Profilers: Frequencies

Radar frequencies used in Meteorology



We will see the performance difference in a minute ...

WIND Profilers: Basics



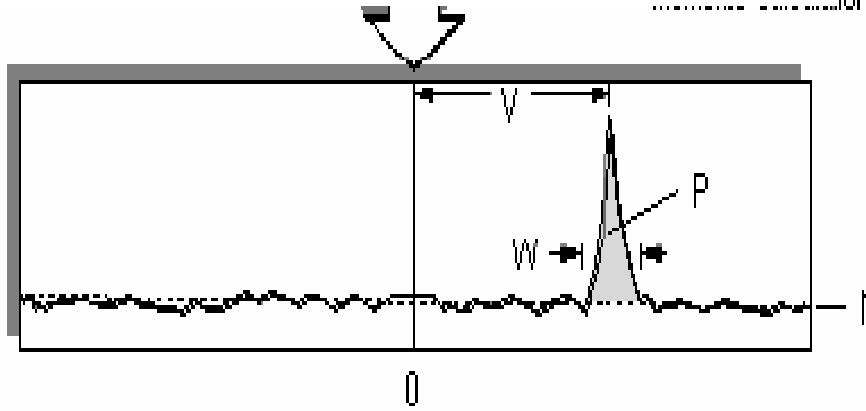
- time to frequency domain conversion
- Spectral averaging, windowing,
- trend removal,
- Noise level detection
- For each level you will get the following

Doppler **Shift** →

$$\bar{f}_D = \frac{\sum_{i=f_1}^{f_2} f_i S(f_i)}{\sum_{i=f_1}^{f_2} S(f_i)}$$

Doppler width →

$$V_D = 2 \sqrt{\frac{\sum_{i=f_1}^{f_2} ((f_i - \bar{f}_D)^2 S(f_i))}{\sum_{i=f_1}^{f_2} S(f_i)}}$$



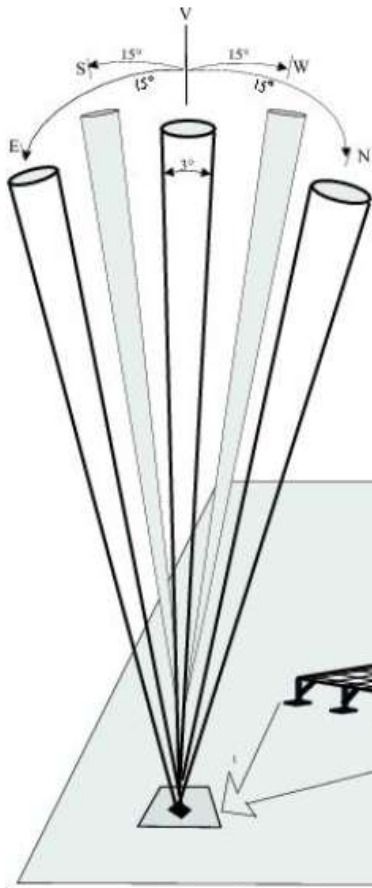
- Noise level: Calculated assuming gaussian noise
- Signal-to-Noise ratio: Ratio power/Noise

4- quantities: Backscattered power ; Noise level; Doppler shift; W: Spectral width

- Quantities calculated at each range gate, beam pointing direction, etc.;
- expressed in decibel (dB) - ratio between two values (e.g. signal-to-noise ratio)

WIND Profilers: From line of site shift to full wind profiling by design

- Estimation of Doppler shift along 3-5 beams
- Calculation of u, v, w from radial velocities



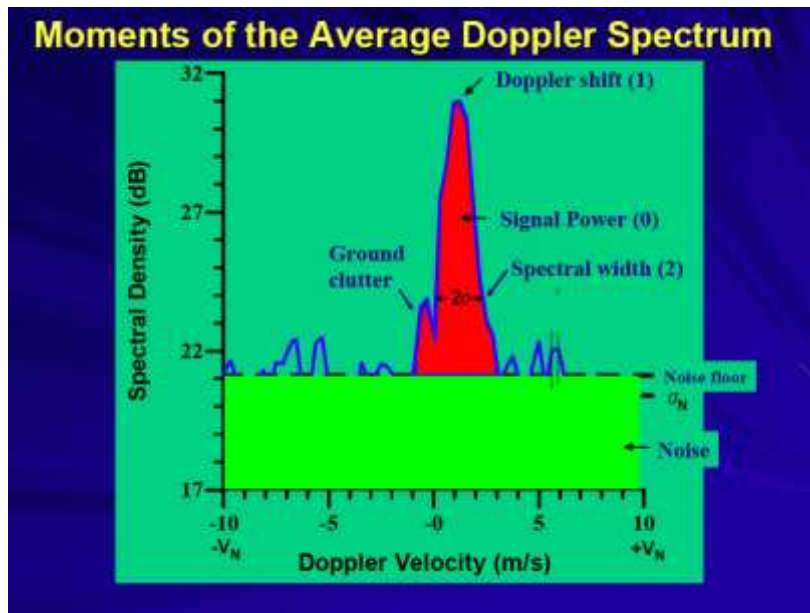
$$\begin{pmatrix} \sin(\alpha_1)\sin(\epsilon_1) & \cos(\alpha_1)\sin(\epsilon_1) & \cos(\epsilon_1) \\ \sin(\alpha_2)\sin(\epsilon_2) & \cos(\alpha_2)\sin(\epsilon_2) & \cos(\epsilon_2) \\ \sin(\alpha_3)\sin(\epsilon_3) & \cos(\alpha_3)\sin(\epsilon_3) & \cos(\epsilon_3) \\ \sin(\alpha_4)\sin(\epsilon_4) & \cos(\alpha_4)\sin(\epsilon_4) & \cos(\epsilon_4) \\ \sin(\alpha_5)\sin(\epsilon_5) & \cos(\alpha_5)\sin(\epsilon_5) & \cos(\epsilon_5) \end{pmatrix} \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} v_{r1} \\ v_{r2} \\ v_{r3} \\ v_{r4} \\ v_{r5} \end{pmatrix}$$

Assumptions:

- Uniform wind field across sampled volume (2.5 km @ z=5 km)
- Stationary wind field over measurement time (~ 30 min)

the system cycles through five beams (South, North, East, West, and vertical) at low power and high power (longer pulse length) setting. In ~ 5 minutes.

WIND Profilers: What else?



Signal processing problem: How to find the signal and uncertainty when you have

- Low SNR
- Noise
- Ground clutter
- Moving clutter targets
- Radio-frequency interference (RFI)
- Aliasing

Assumptions:

- Moments input is of good quality
- Wind field is close to linear
- Vertical wind has no horizontal shear
- The wind field is stationary in time and space

Maximize your confidence (QC):

Consensus Time (e.g. 30 min; ARM ~ 1hr)

- Consensus Window (e.g. $W=2$ m/s)
- Consensus Threshold (e.g. $P=60\%$)

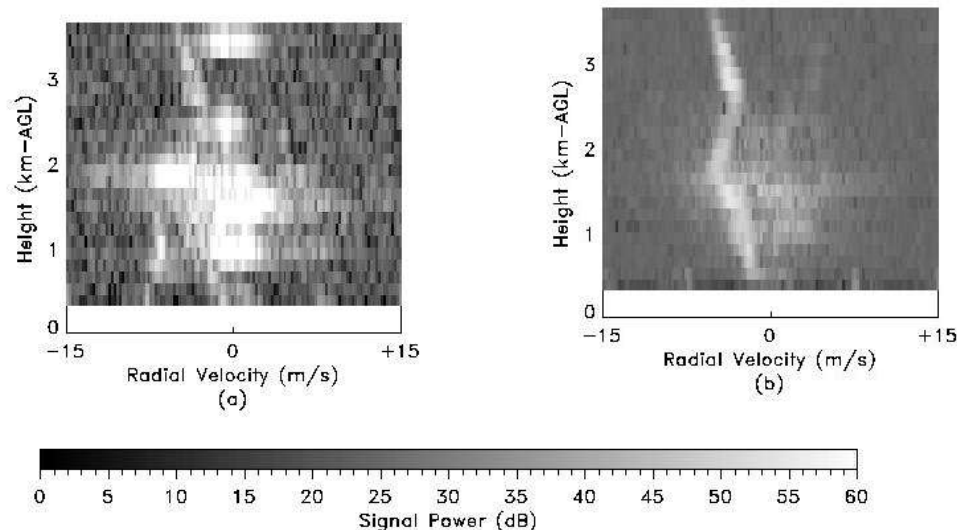
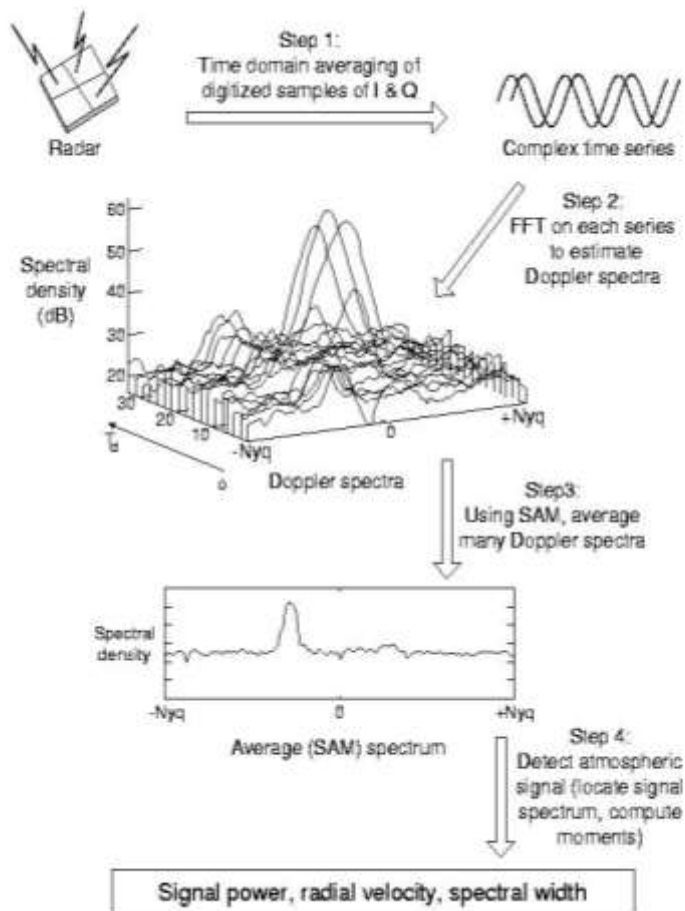
Question: Can we find a window of W m/s that contains at least P (%) of the measured velocities?

- No....no value reported
- Yes...value reported is the mean of the points within the defined window

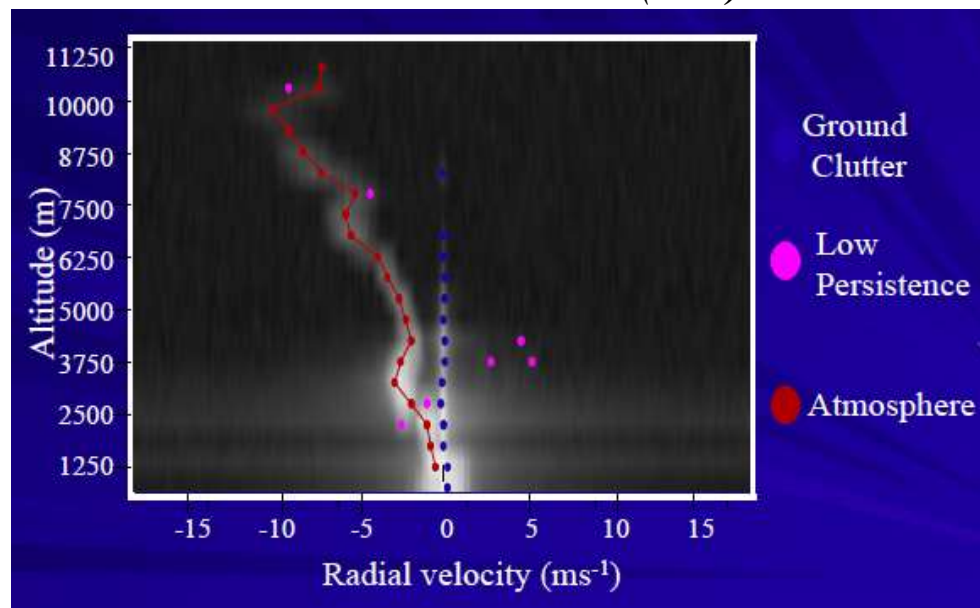
WIND Profilers: Processing – many methods

SATISTICAL AVERAGING METHOD (SAM)

Merritt D.A. 1995 JTech 12

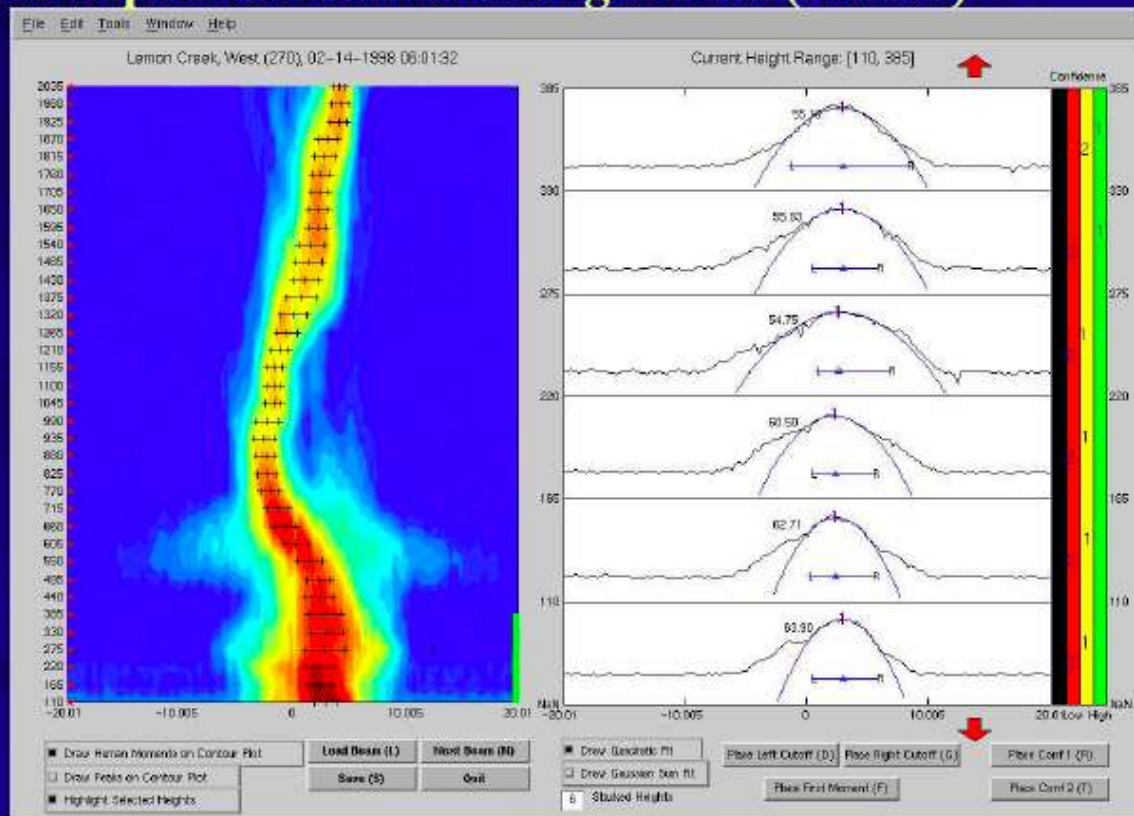


Clothiaux et al. JTech 11 (1994)



Fuzzy Logic: Global Image Processing

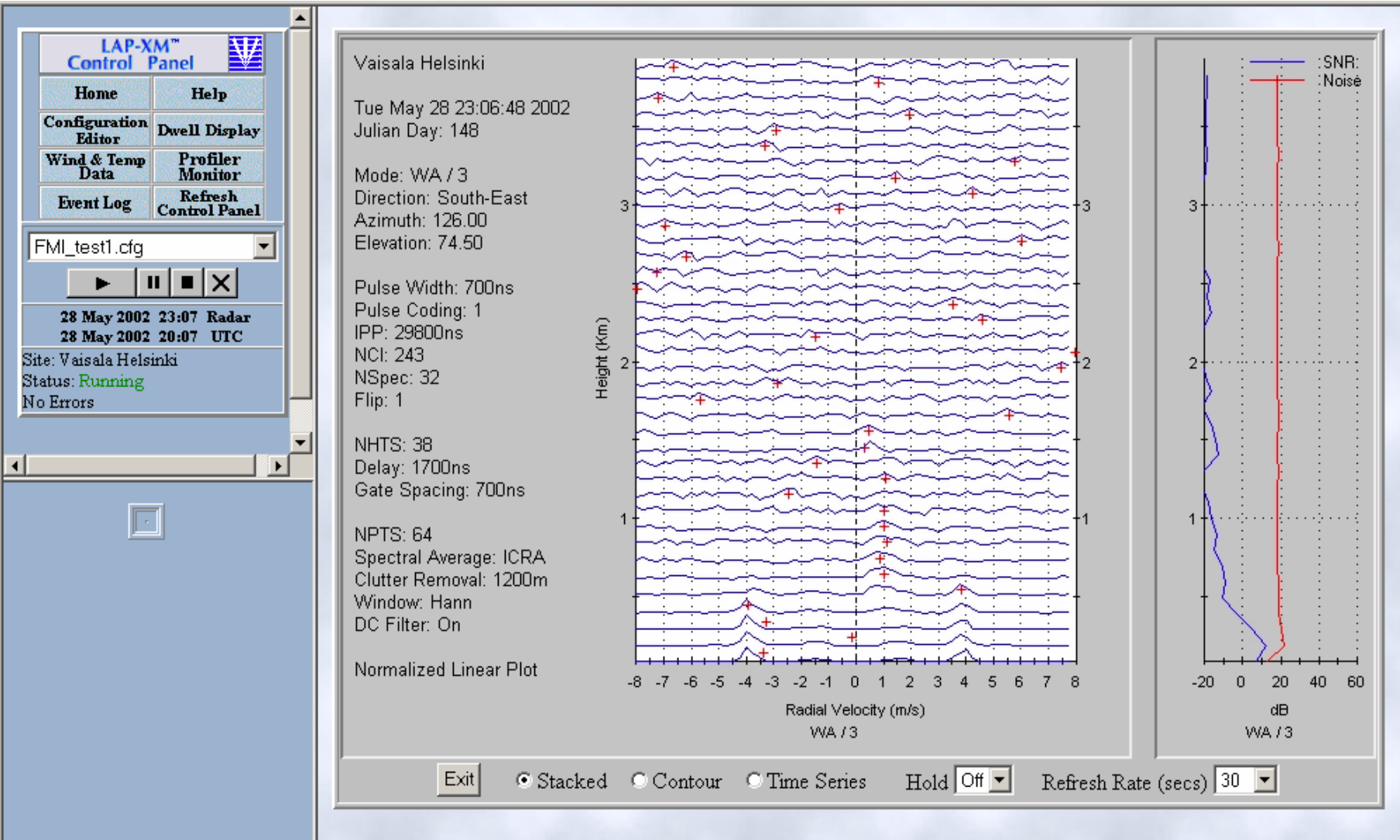
NCAR Improved Moments Algorithm (NIMA)



Cohn et al. 2001, JAM 40, 704-719

Cohn et al. 2001, JAM 40, 704-719

WIND Profilers: Find the signal



If no COVID-19 you would see this at Beltsville

WIND Profilers: What data do we get?

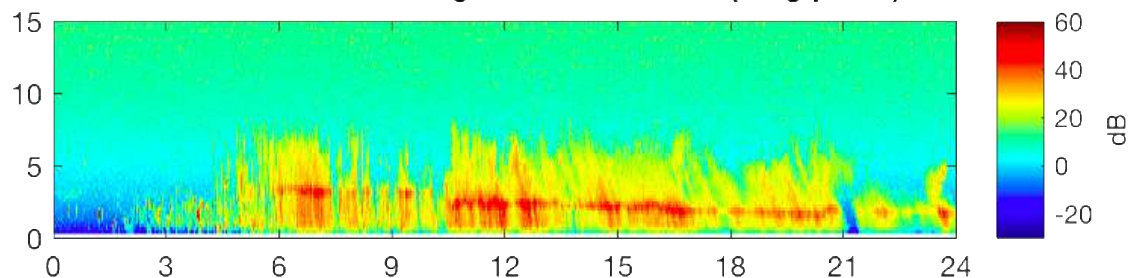
5.2.1.1 Wind Profile Data

- Spectral Data
 - At each height, beam pointing direction, and power level:
 - Spectral amplitude (at each bin of FFT).
- Moments Data
 - At each beam pointing direction, and power level:
 - At each range gate:
 - Mean Doppler shift (in % of Nyquist frequency)
 - Spectral width (in % of Nyquist frequency)
 - SNR level (in dB)
 - Noise level (in dB)
- Average Data
 - At each power level:
 - At each range gate:
 - Wind speed (in m/s)
 - Wind direction (degrees relative to true north)
 - For each beam pointing direction:
 - Radial wind speed (positive = toward the antenna)
 - Number of moments that passed consensus criteria
 - Average SNR

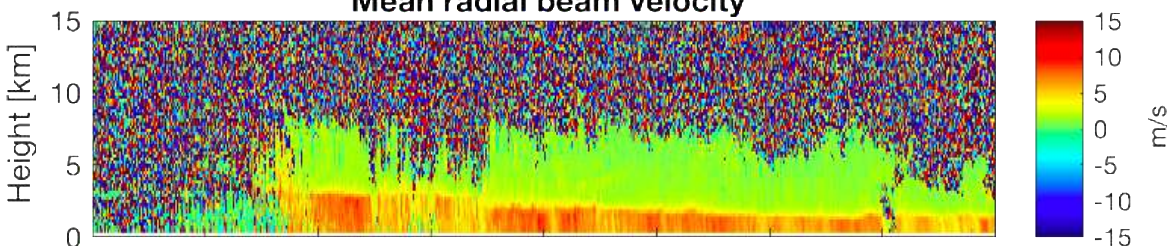
This is basically what you need as a user ...

WIND Profilers: example

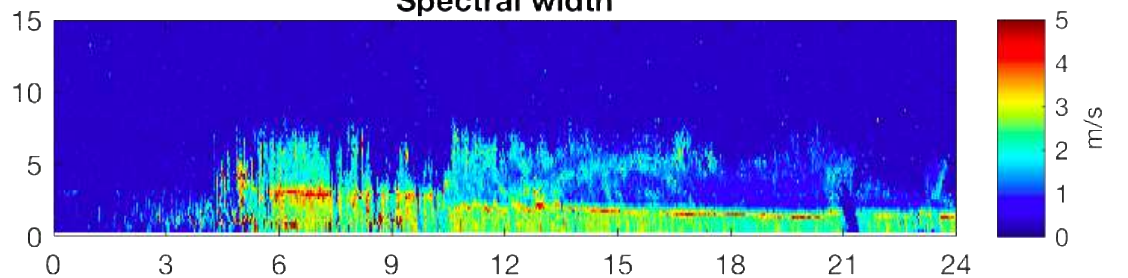
SGP I9 2018-04-21: Range corrected SNR (long pulse)



Mean radial beam velocity



Spectral width



Time [UTC]

Discuss:

“Note that the vertical velocity definition is such that positive is downward, towards the antenna. In this example, the vertical velocities, the SNR, and the spectral width are all affected by rainfall (large downward motion associated with energy scattered from falling rainfall rather than atmospheric structure) at about 0500 UTC until the end of the day.”

*Calculated moments for the **vertical beam** at SGP I9, Billings, Oklahoma on 2018-04-21. [ARM 915 Handout]*

WIND Profilers: What to watch for

Wind measurement uncertainty considerations

$$\text{Total uncertainty} = \text{Instrument uncertainty} + \text{Retrieval uncertainty} + \text{Representativity}$$

Pulse and beam forming, temporal sampling/ranging

Estimation of Doppler shift over large dynamic range (SNR)

Removal of clutter (ground & bird echoes) and radio frequency interference

Wind vector retrieval from radial velocities:

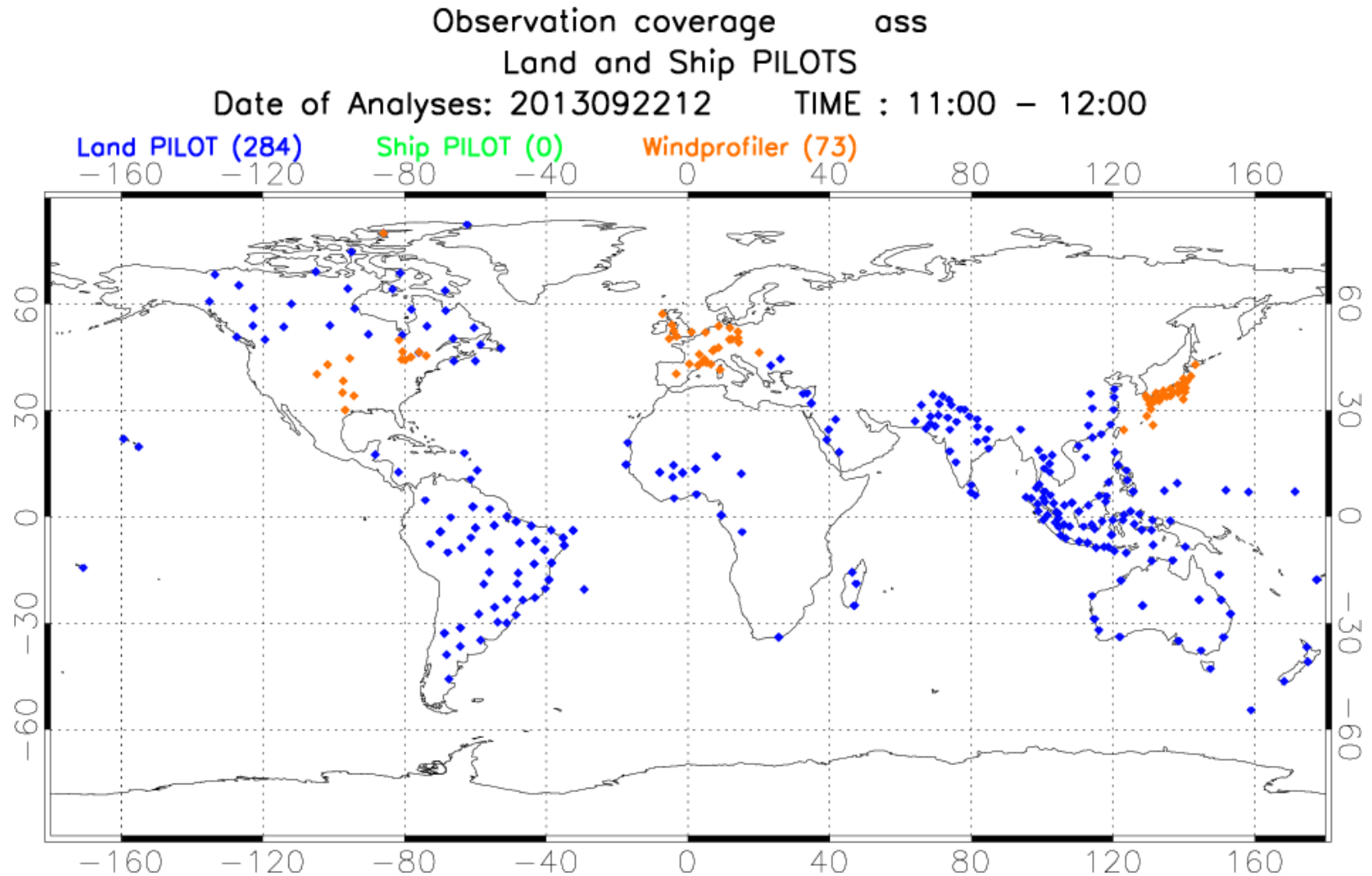
Spatial sampling aspects: # of beams, elevation(s) & azimuths

Horizontal homogeneity and stationarity of wind field required - averaging

Atmospheric variability & mismatch between observation and model scale

Partly accounted for by temporal integration

WIND Profilers: Where are they located



Check out Japan

WIND Profilers: many types



Radiometrics, Corp.
4909 Nautilus Court North, Suite 110
Boulder, CO 80301 USA
T (303) 449-9192 www.radiometrics.com

RAPTOR™ Radar Wind Profiler Models

Radiometrics, Corp. designs and manufactures a full line of radar wind profilers (RWPs). The different models are designed for various applications to allow the customer to choose the best system for their specific requirements. Most RAPTOR systems can be customized for user requirements. Please consult the Radiometrics factory or your representative for further information.

Table 1: RAPTOR Radar Wind Profiler Models by Atmospheric Height

RAPTOR Model	Atmosphere Level	Typical Height ¹	Frequency Band	Description
<i>DBS-BL</i>	Boundary Layer	3-4 km	900 – 1400 MHz	Upgrade for LAP ² -3000 ²
<i>FMC-BL</i>		1-3 km	900 – 1400 MHz	Designed for shipboard installation
<i>XBS-BL</i>		3-4 km	900 – 1400 MHz	Lower cost; designed for trailer or static mount
<i>VAD-BL</i>		3-6 km	900 – 1400 MHz	High-performance stationary system
<i>XBS-T</i>	Troposphere	5-8 km	400 – 500 MHz	Lower cost; designed for trailer or static mount
<i>FBS-T</i>		5-8 km	400 – 500 MHz	Scalable antenna and transmitter
<i>FBS-ST</i>	Troposphere/Stratosphere	16 km	400 – 500 MHz	Scalable antenna and transmitter
<i>FBS-ST-EX</i>		18 km	200 MHz	Scalable antenna and transmitter
<i>FBS-MST</i>		20 km	50 MHz	Scalable antenna and transmitter

*See in
altitude
and
frequency?*

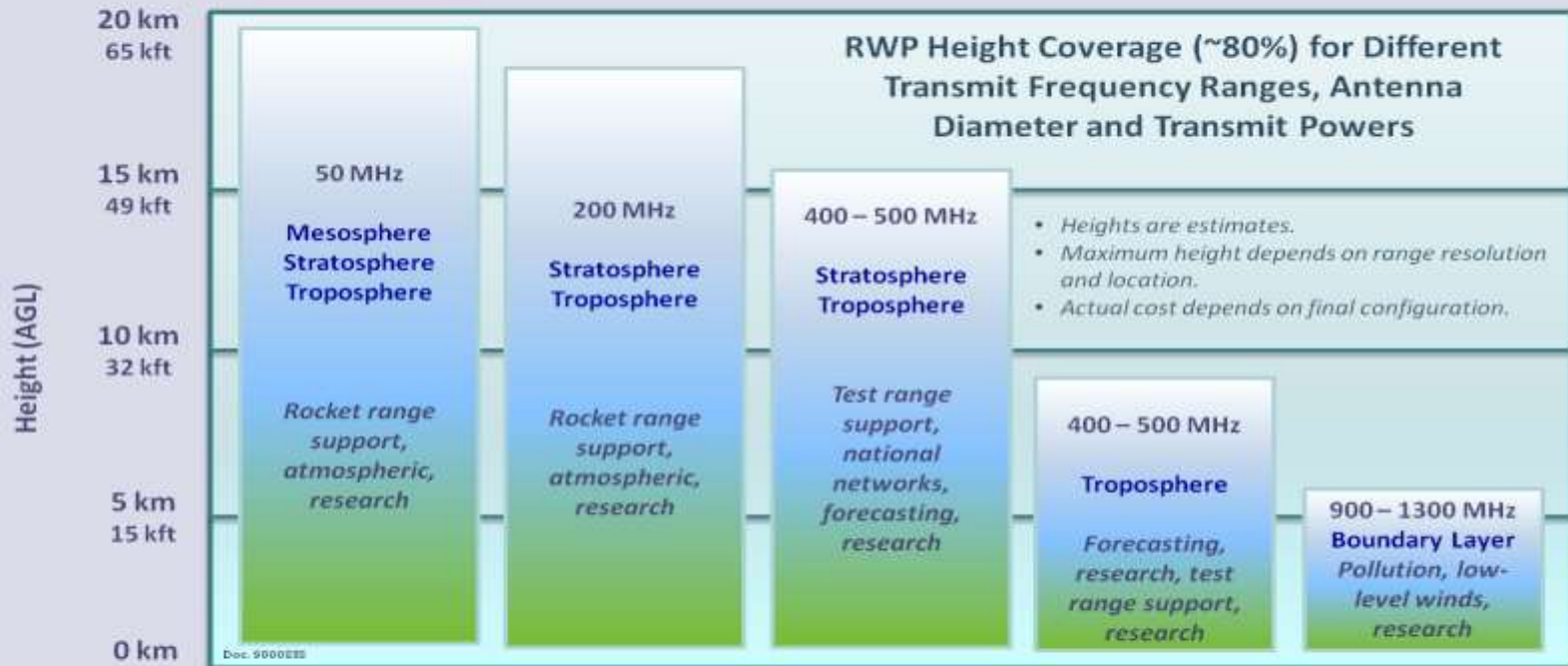
Acronyms: DBS – Doppler Beam Swinging, FMC – Full Motion Control, XBS – Hexagonal Beam Steering, VAD – Velocity Azimuth Display, FBS – Full Beam Steering, BL – Boundary Layer, T – Troposphere, S – Stratosphere, M – Mesosphere, EX – Extended.

A Radio Acoustic Sounding System (RASS) is available for all models or can be integrated with a Radiometrics radiometer system. Radiometrics also builds S- and X- band vertical hydro-meteorological radars and can customize all models.

¹ Maximum height is listed for clear-air and is highly dependent on geographical latitude and local climatology. Please check with the factory for maximum height estimate for your specific location. For boundary layer systems, rain improves maximum height.

² LAP is a registered trademark of Scintec Corp. These systems were formerly manufactured by Vaisala, Radian, and NOAA.

WIND Profilers: Frequencies



Models:	FBS-MST	FBS-ST-EX	FBS-ST	FBS-T, XBS-T	VAD-, XBS-, FMC-BL
Antenna Size:	125 m	24 m	12 m	6 m	2 m
Peak Power:	125 – 250 kW	24 kW	8 – 12 kW	2 – 4 kW	800 – 2000 W

You can do wind in any frequency – just be careful of errors

WIND Profilers: come in different sizes



MDE profiler @ BV

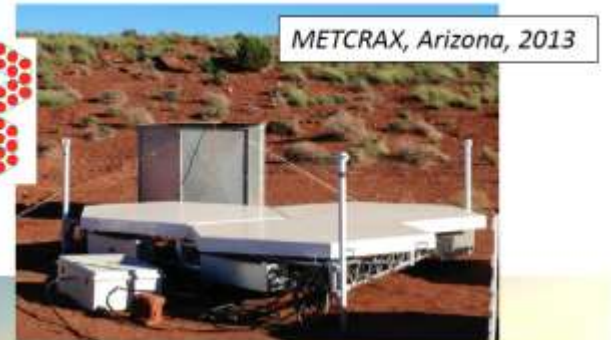
WIND Profilers: come in different sizes

150 m diameter antenna *Stratosphere-Troposphere 50 MHz Radar Wind Profiler .*

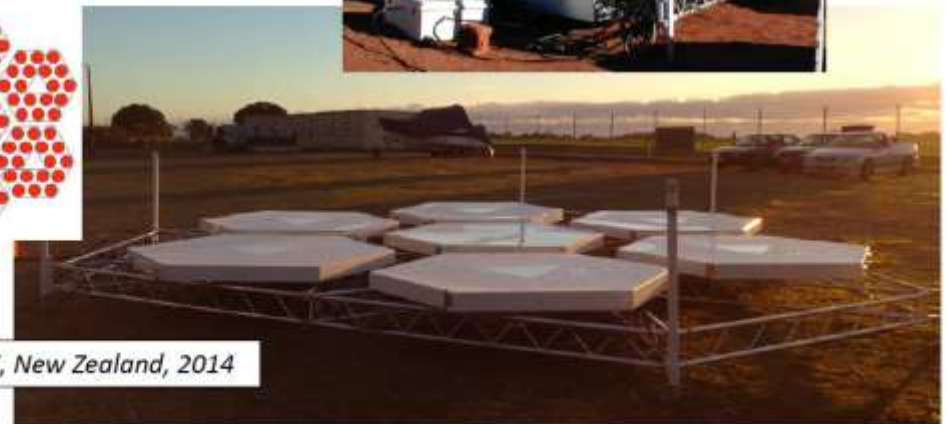


SA 449 MHz RWP

Courtesy:
Bill Brown



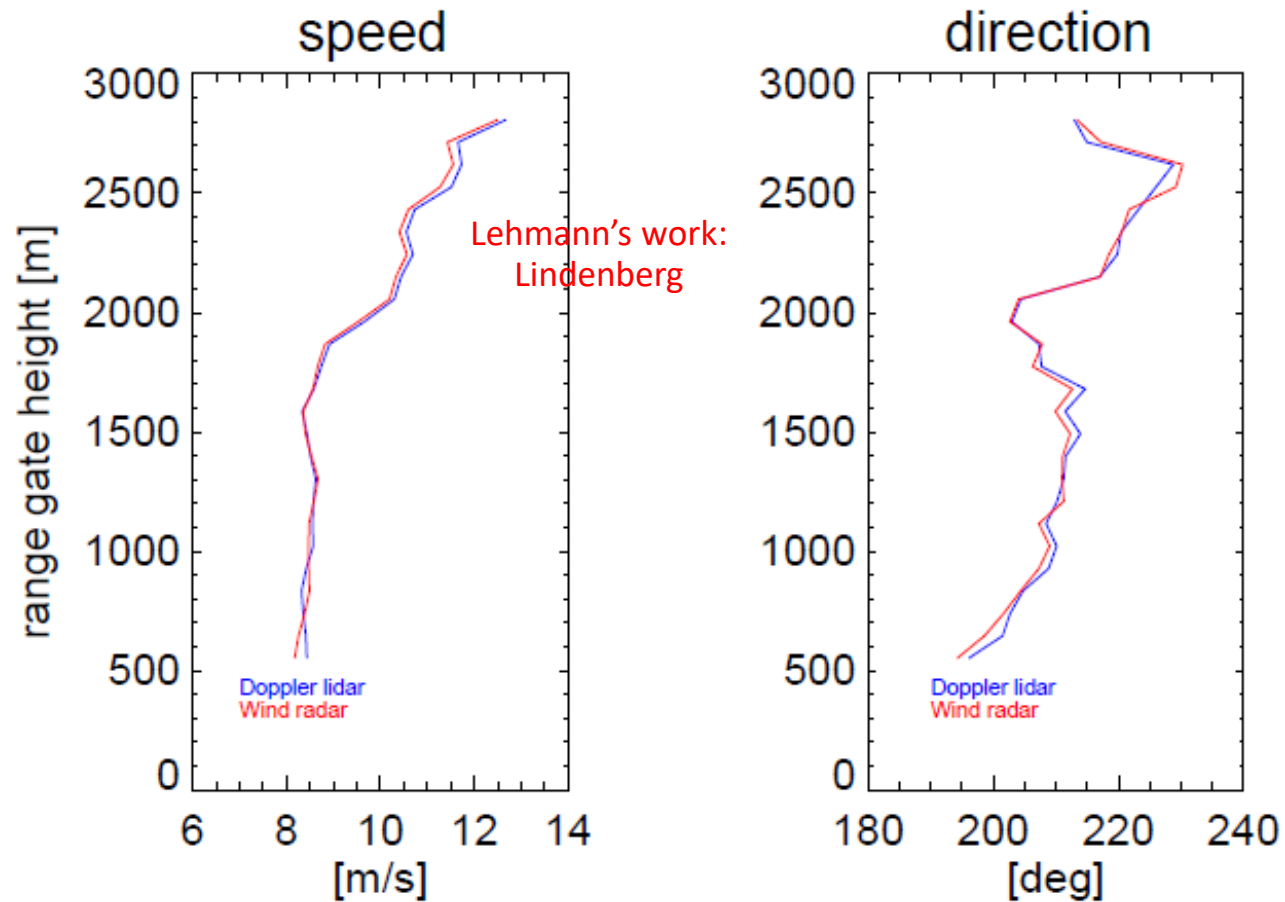
DEEPWAVE, New Zealand, 2014



NCAR's modular design: Steve Cohen's work



WIND Profilers: How good?



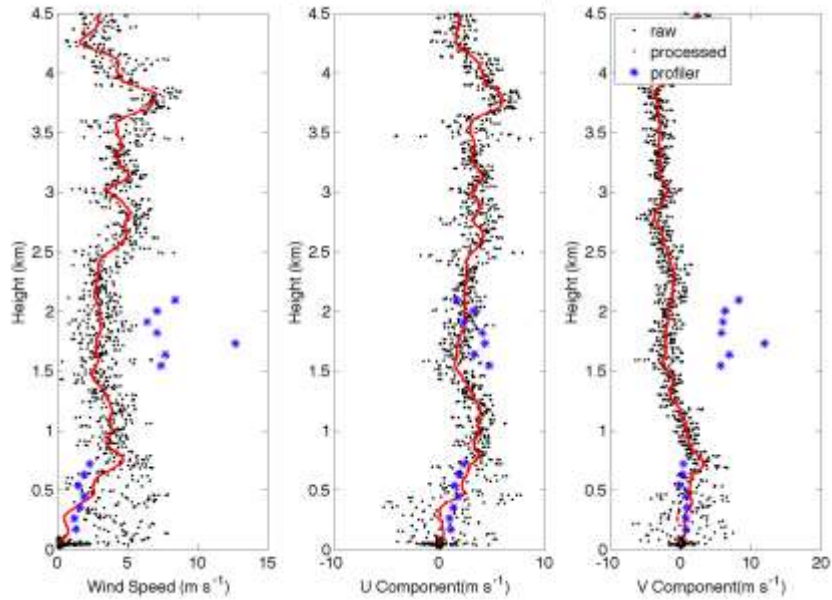
Discuss:

- *Kevin's work*
- *Henry's work – Task for hands-on*

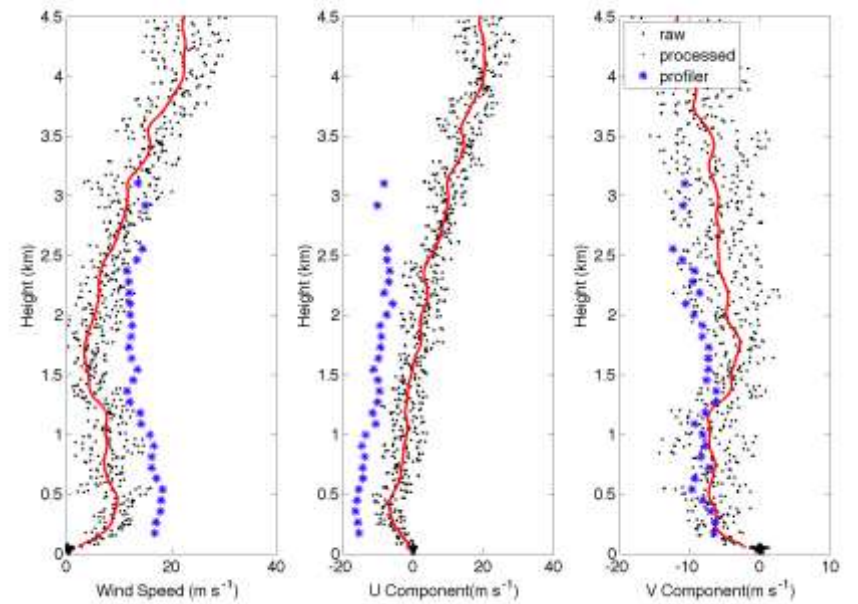
WIND Profilers Vs Sonde *(Intern: Marry Morris*)*

**Now at JPL; PhD in Michigan,*

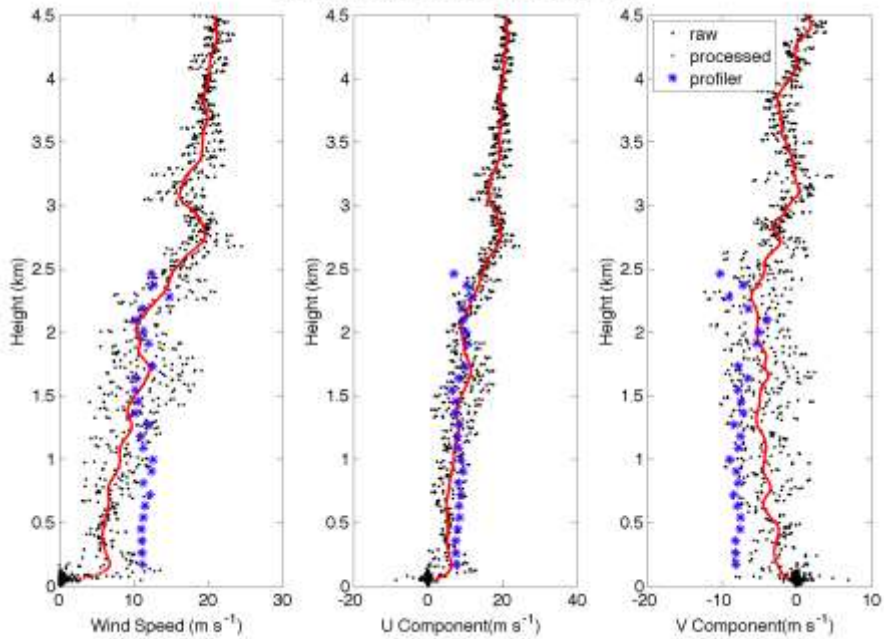
Comparison at 15:00 UTC on 01 Sep 2010



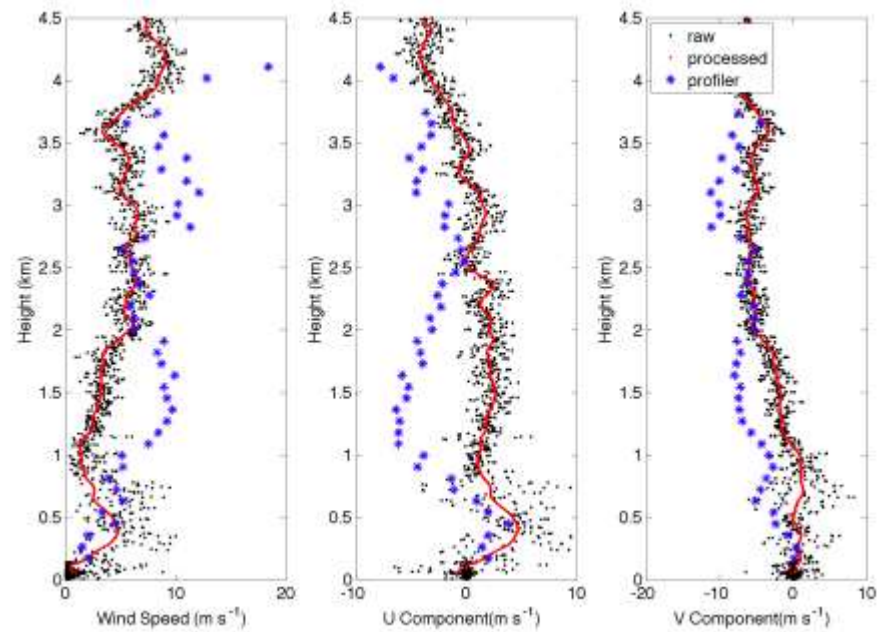
Comparison at 06:00 UTC on 02 Nov 2010



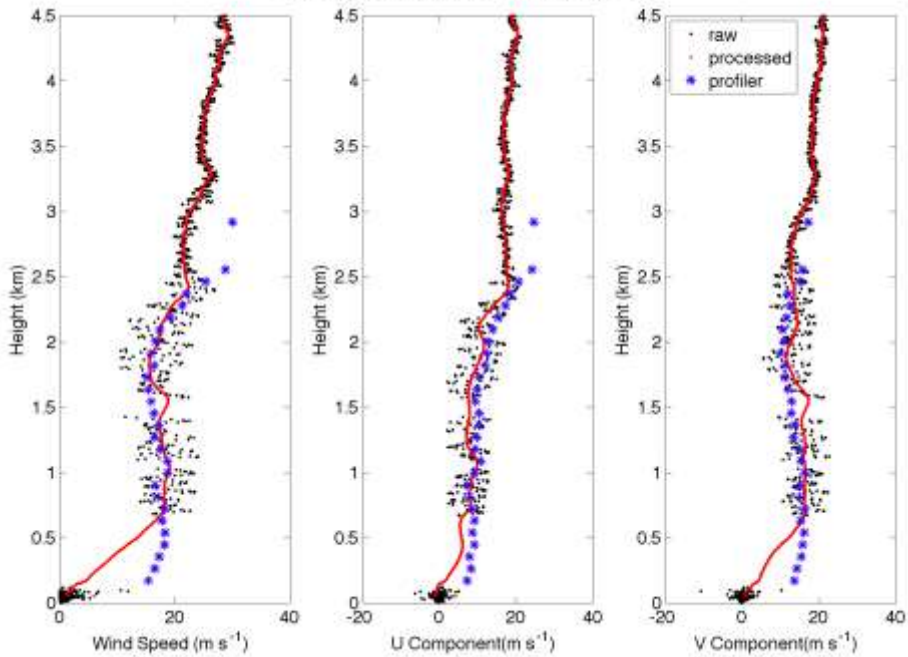
Comparison at 18:45 UTC on 06 Aug 2010



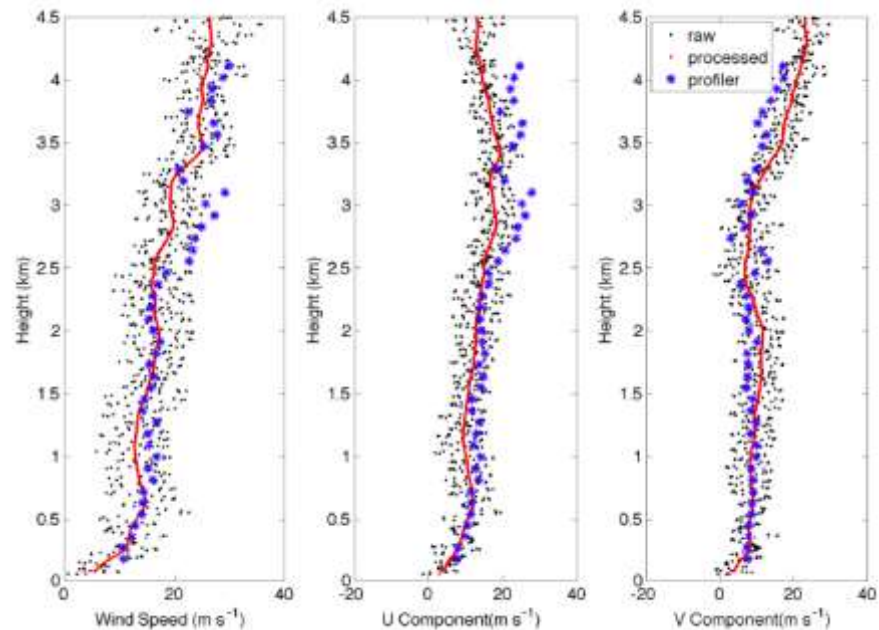
Comparison at 04:15 UTC on 21 Aug 2010



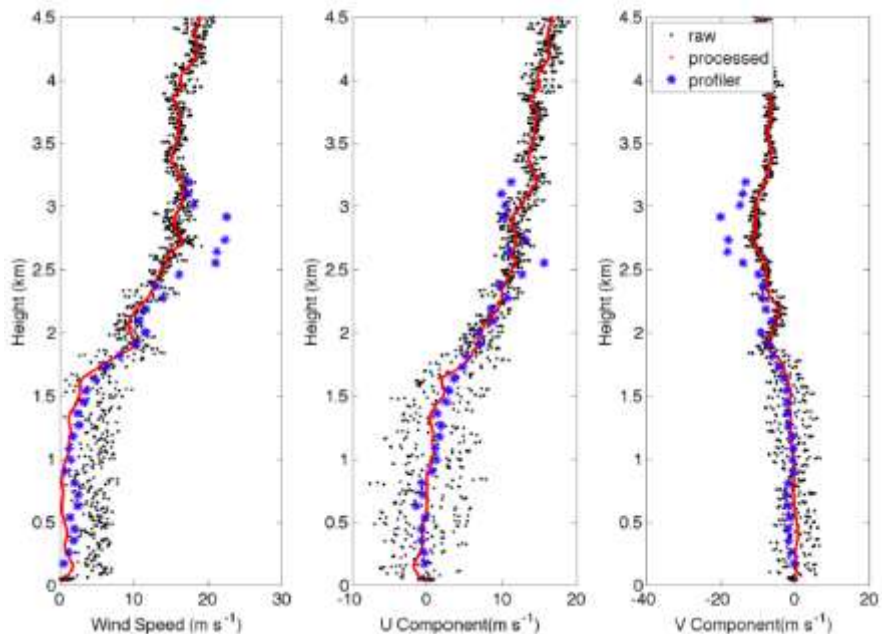
Comparison at 20:15 UTC on 08 Apr 2010



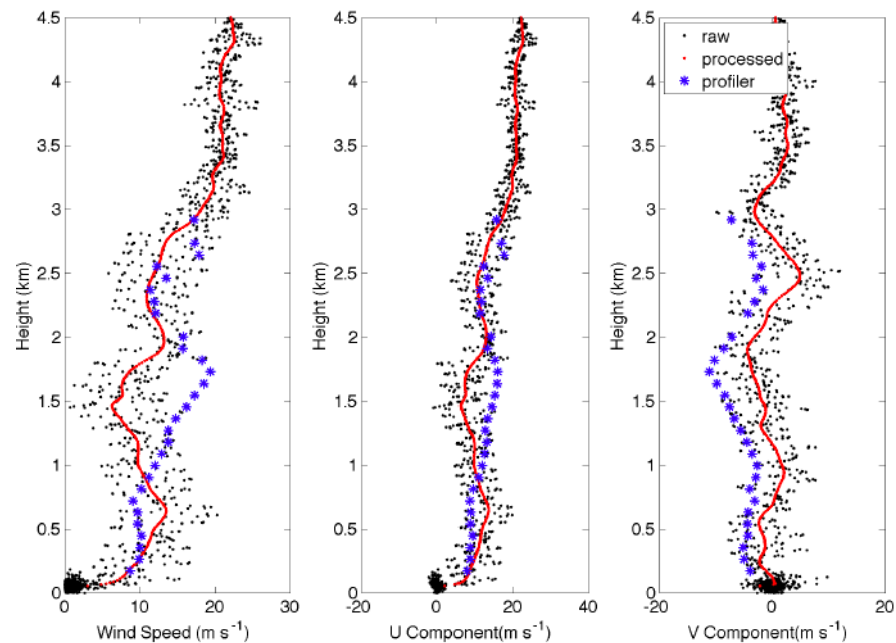
Comparison at 23:00 UTC on 08 Apr 2010



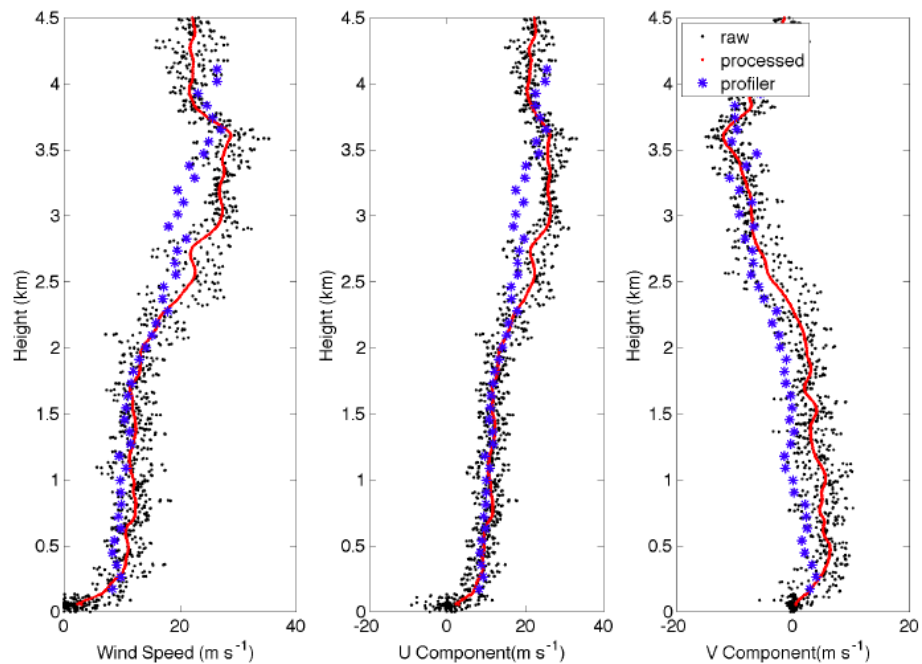
Comparison at 18:30 UTC on 11 Jun 2010



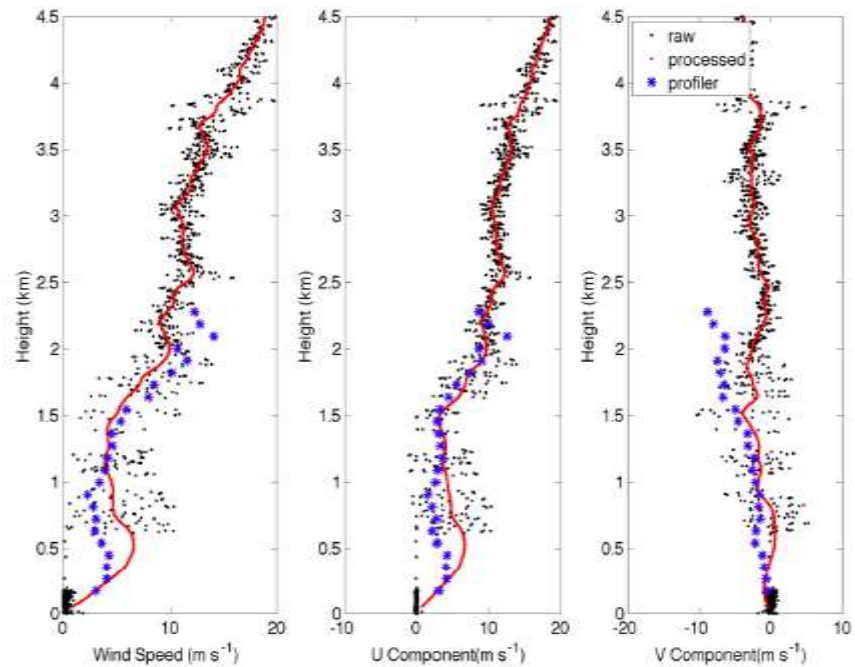
Comparison at 16:00 UTC on 24 Jun 2010



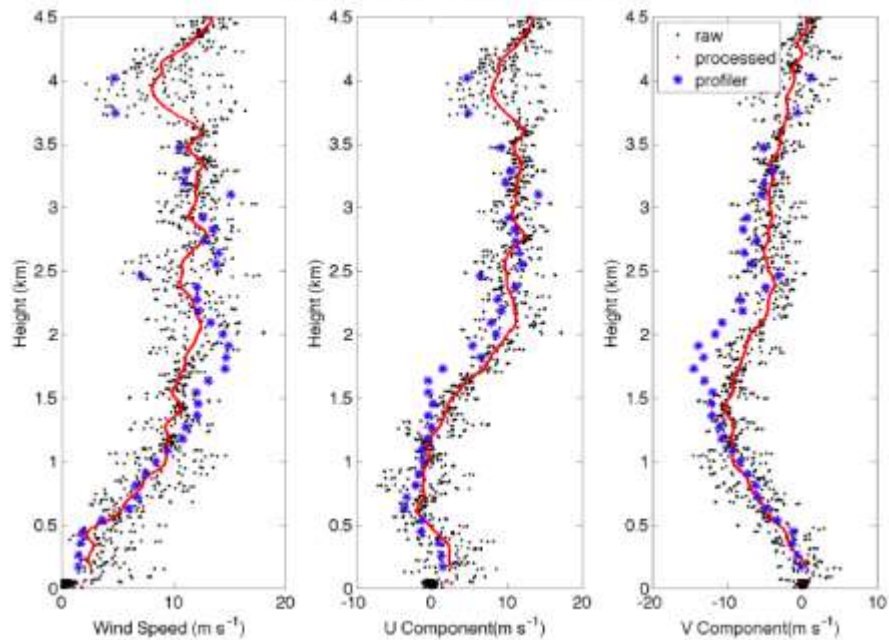
Comparison at 19:45 UTC on 24 Jun 2010



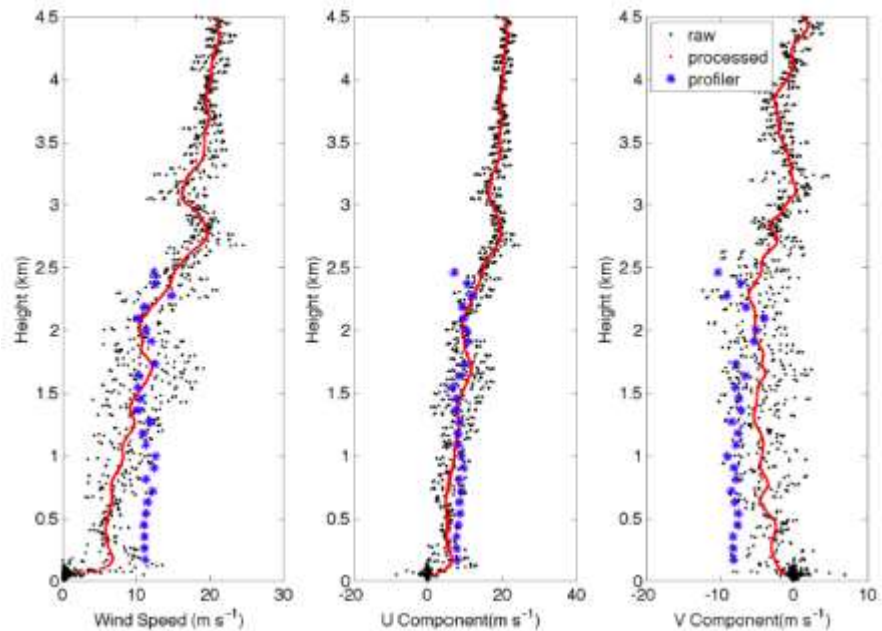
Comparison at 16:30 UTC on 29 Jul 2010



Comparison at 23:15 UTC on 29 Jul 2010

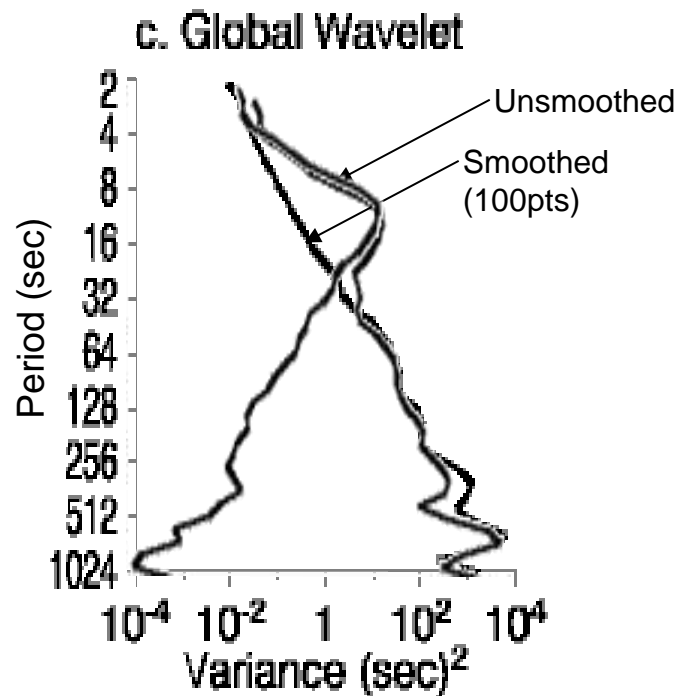
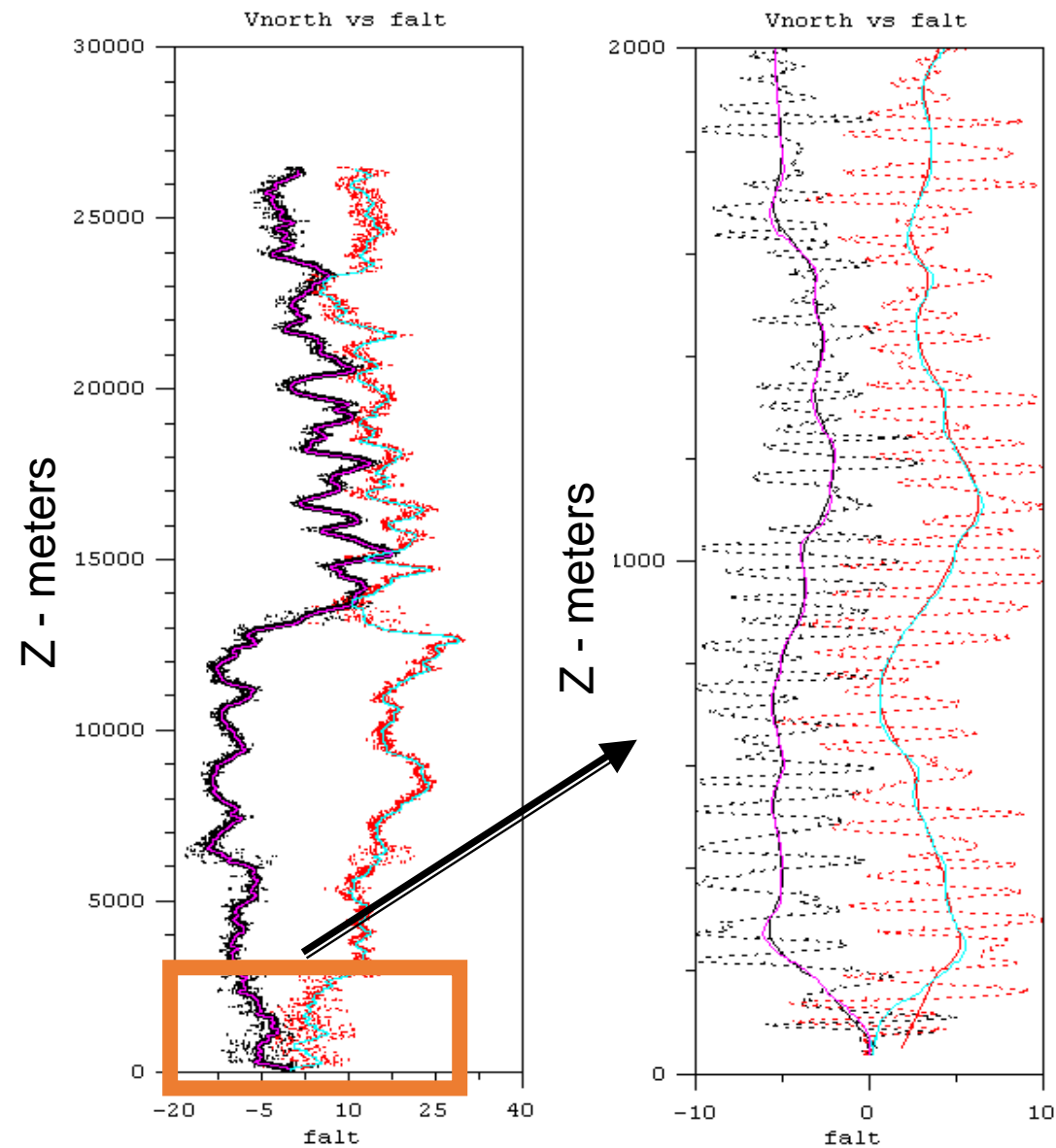


Comparison at 18:45 UTC on 06 Aug 2010

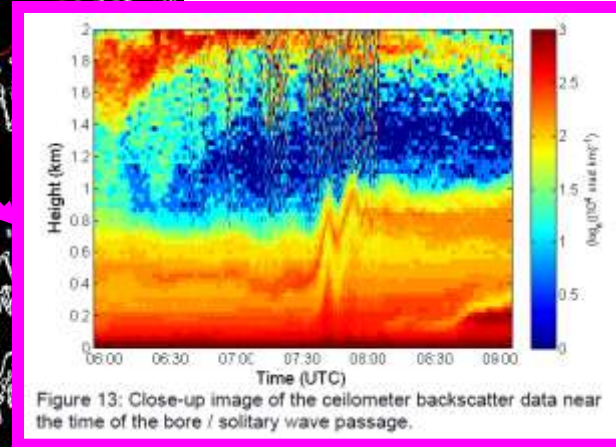
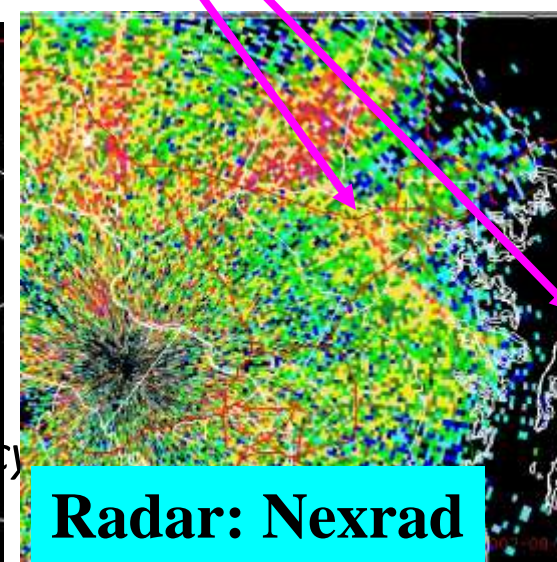
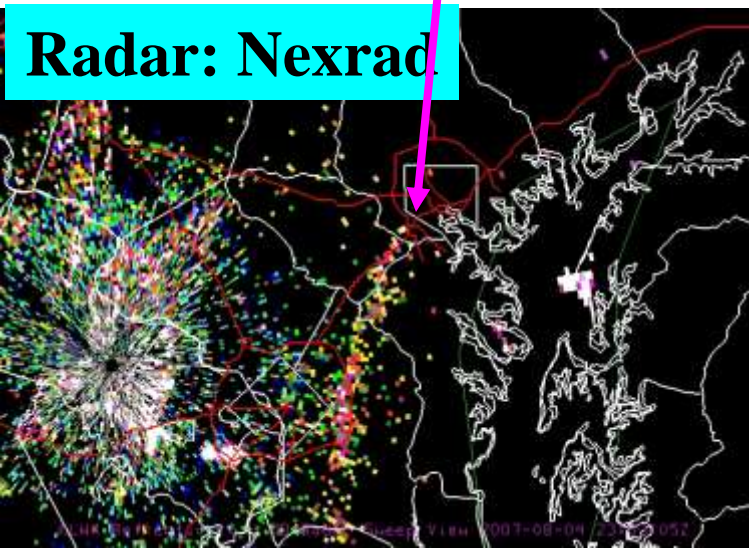
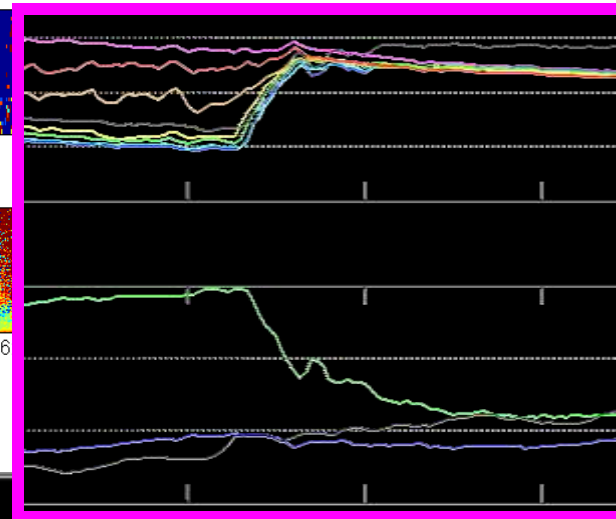
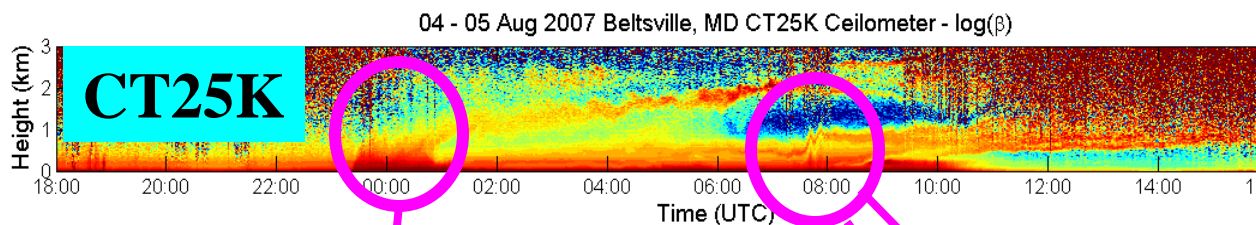
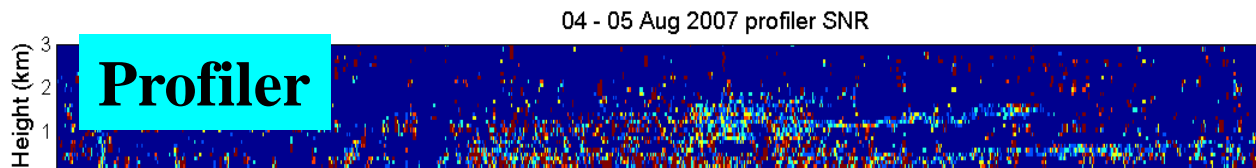
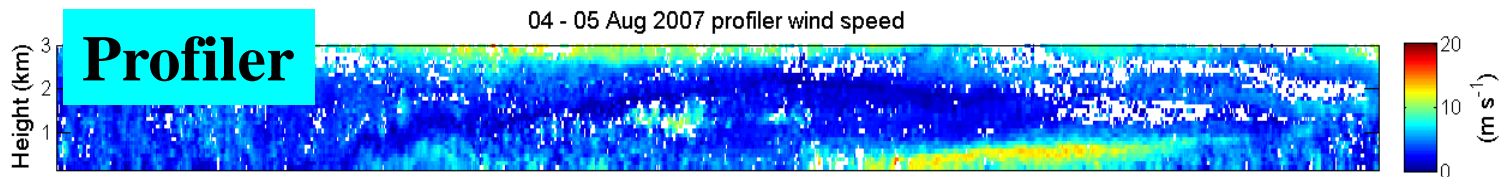


Caution: *Wind from sondes*

- Highly variable < 2km region
- 100pts smooth may be overkill
- Implications to lidar winds?



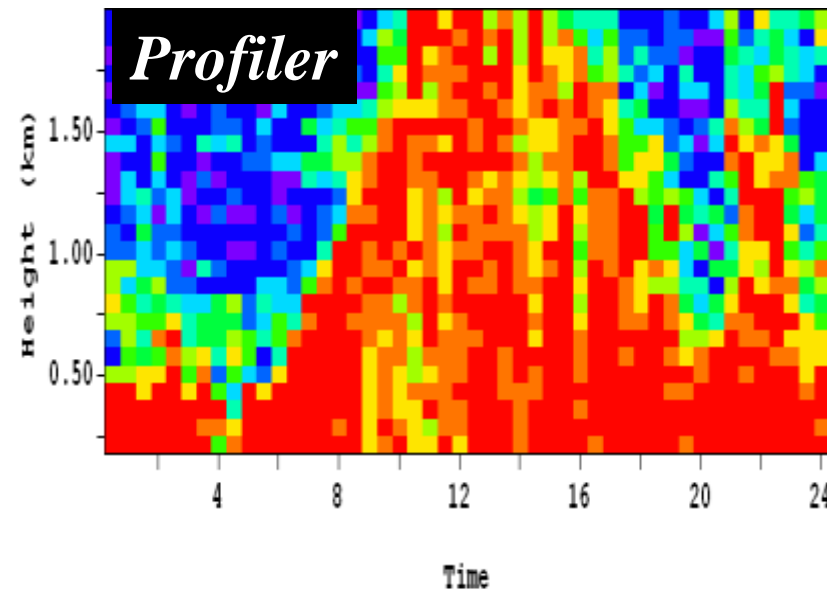
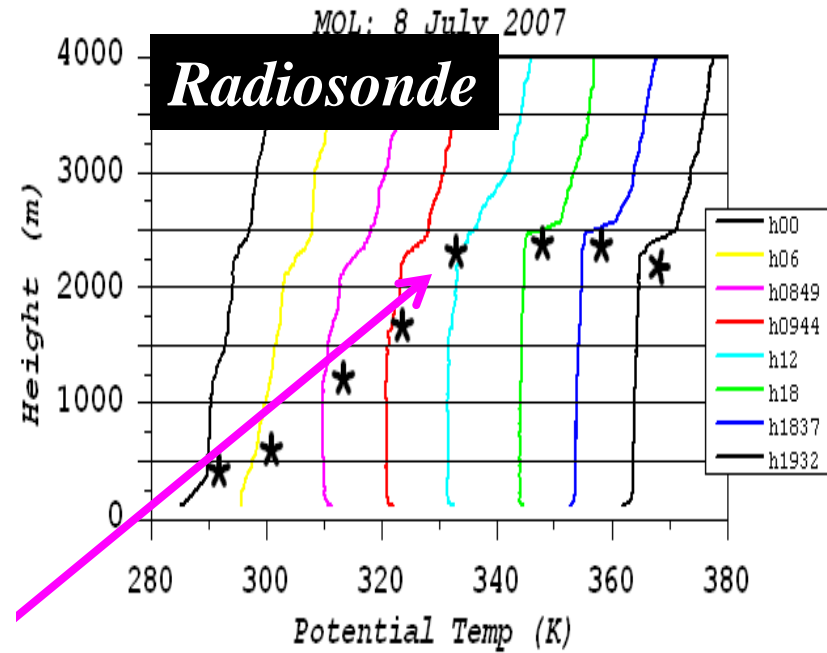
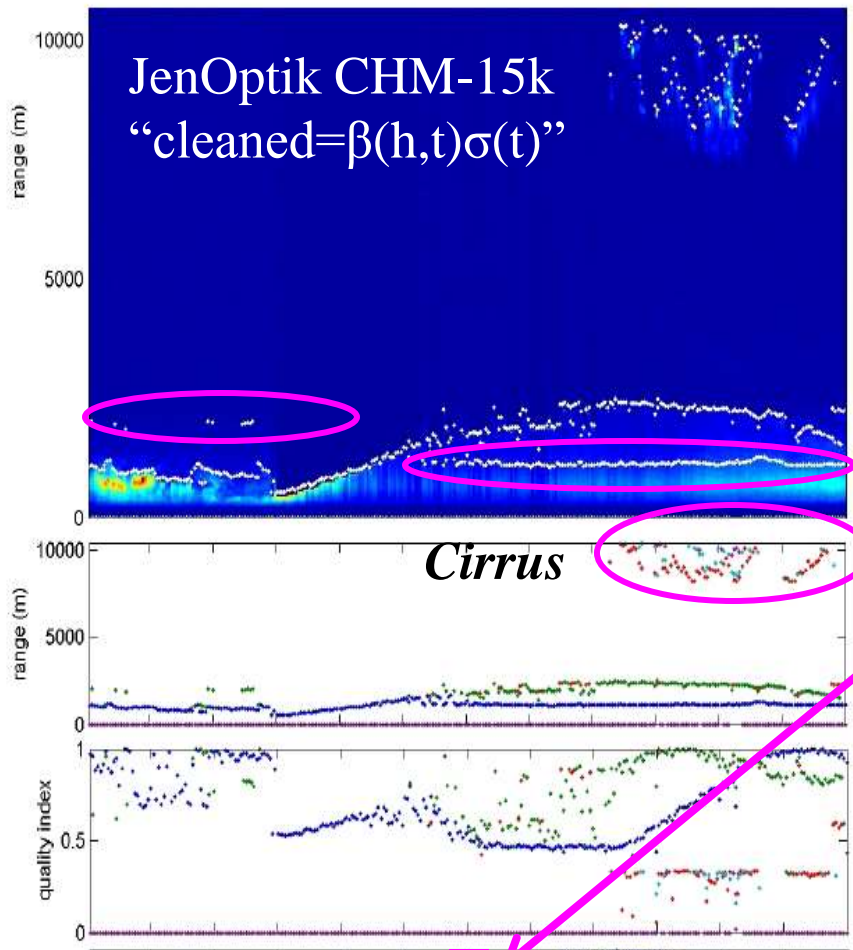
WIND Profilers: Applications



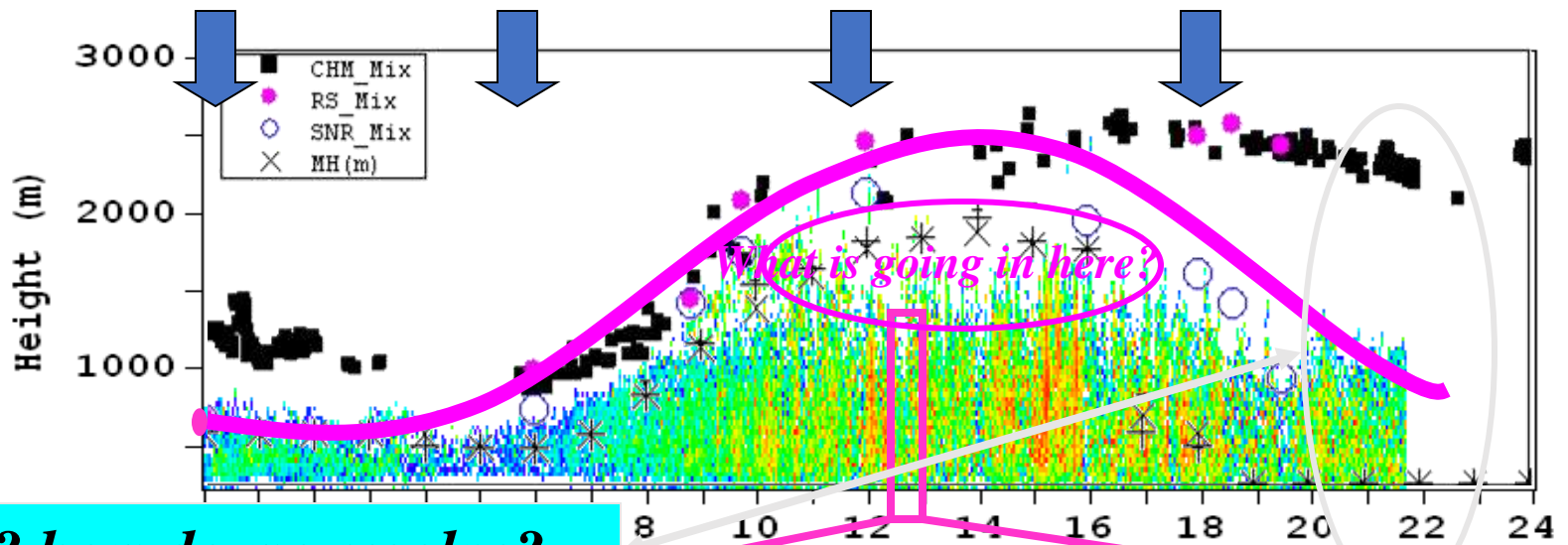
WIND Profilers: Use for PBLH:

Remember Ruben's ceilometer presentation?

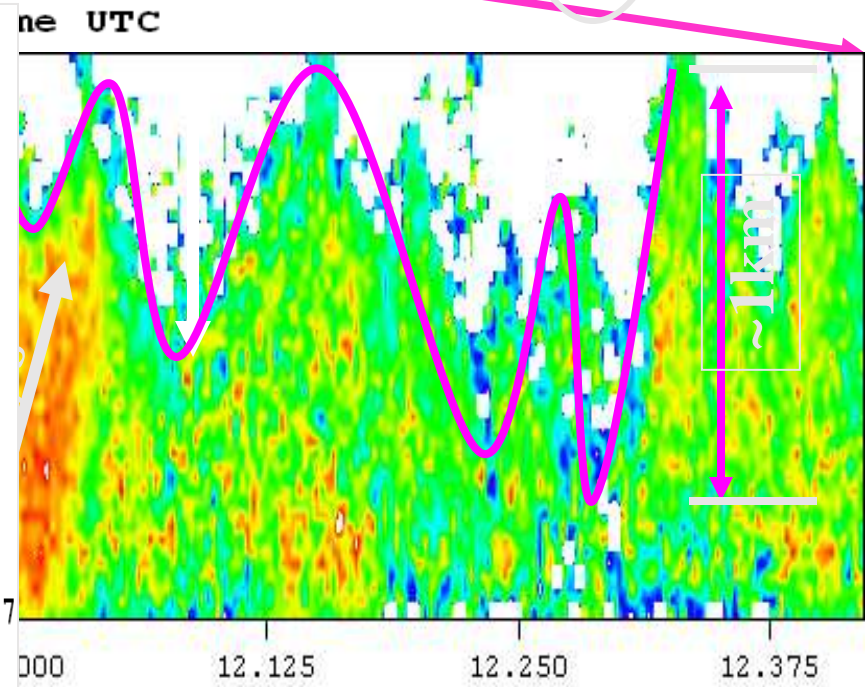
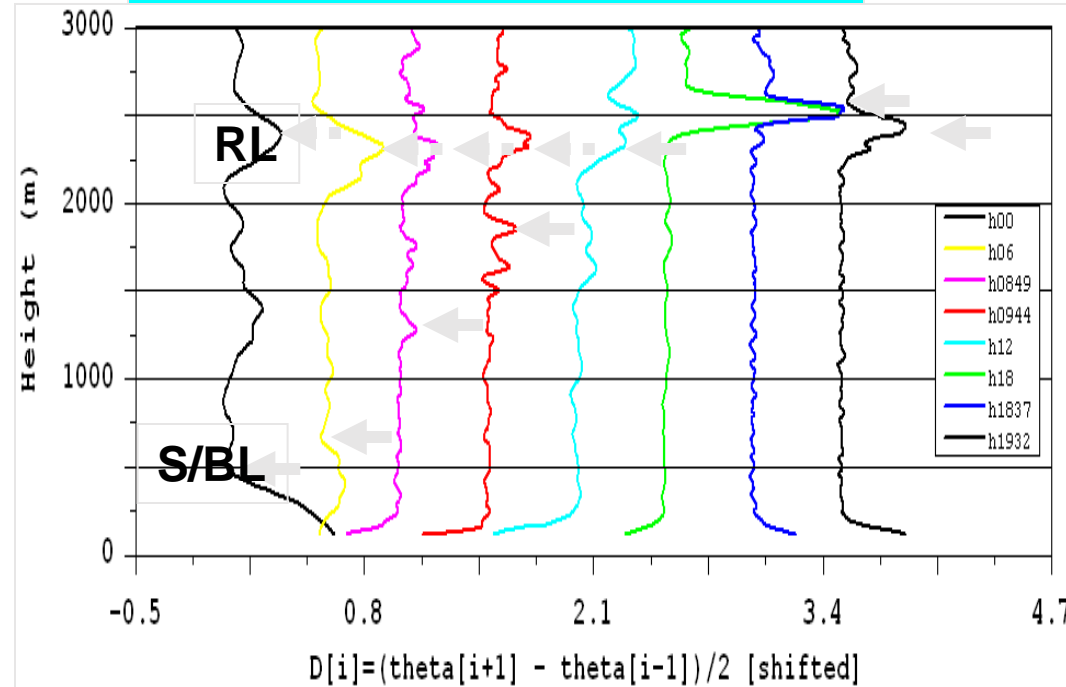
MOL: Ancillary BL data



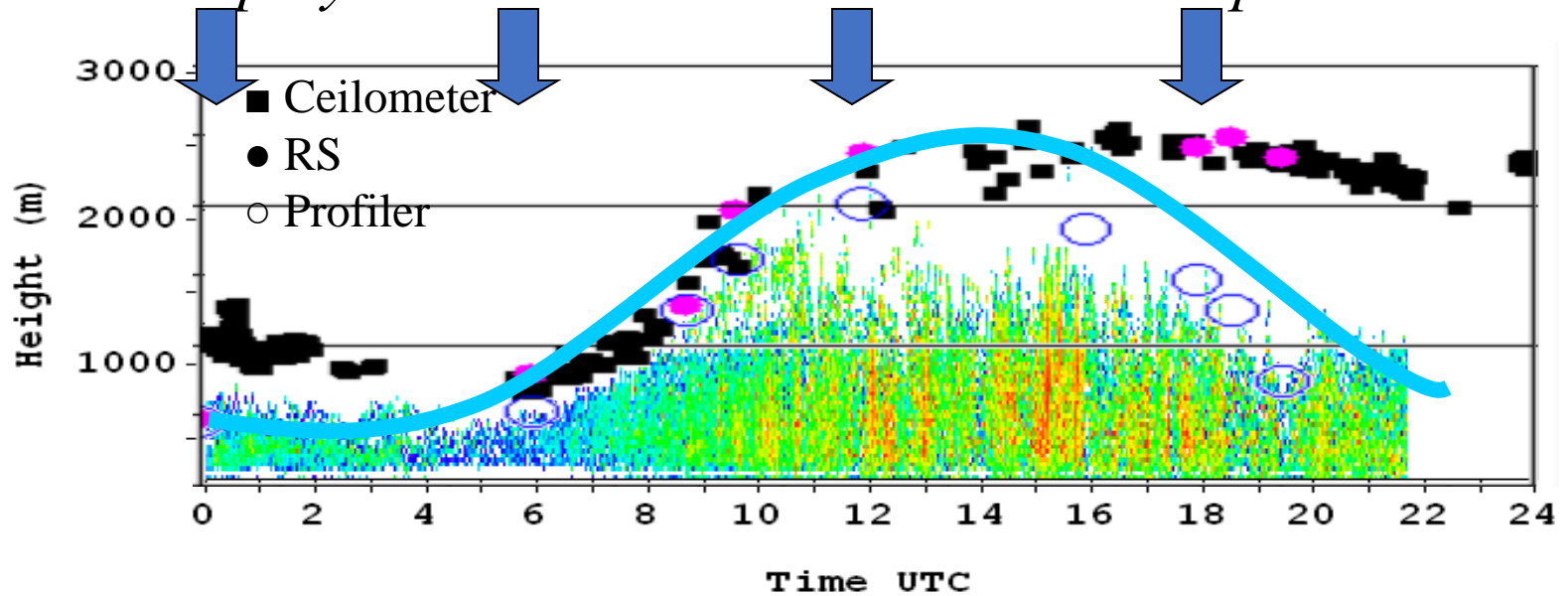
Composite: Radar Reflectivity, Sonde, Profiler



RL? how do we resolve?



Profilers a role to play in PBLH discussion: Jamie Compton's work



Best way to detect PBLH is to consider a “quality factor/weight” to each instrument and

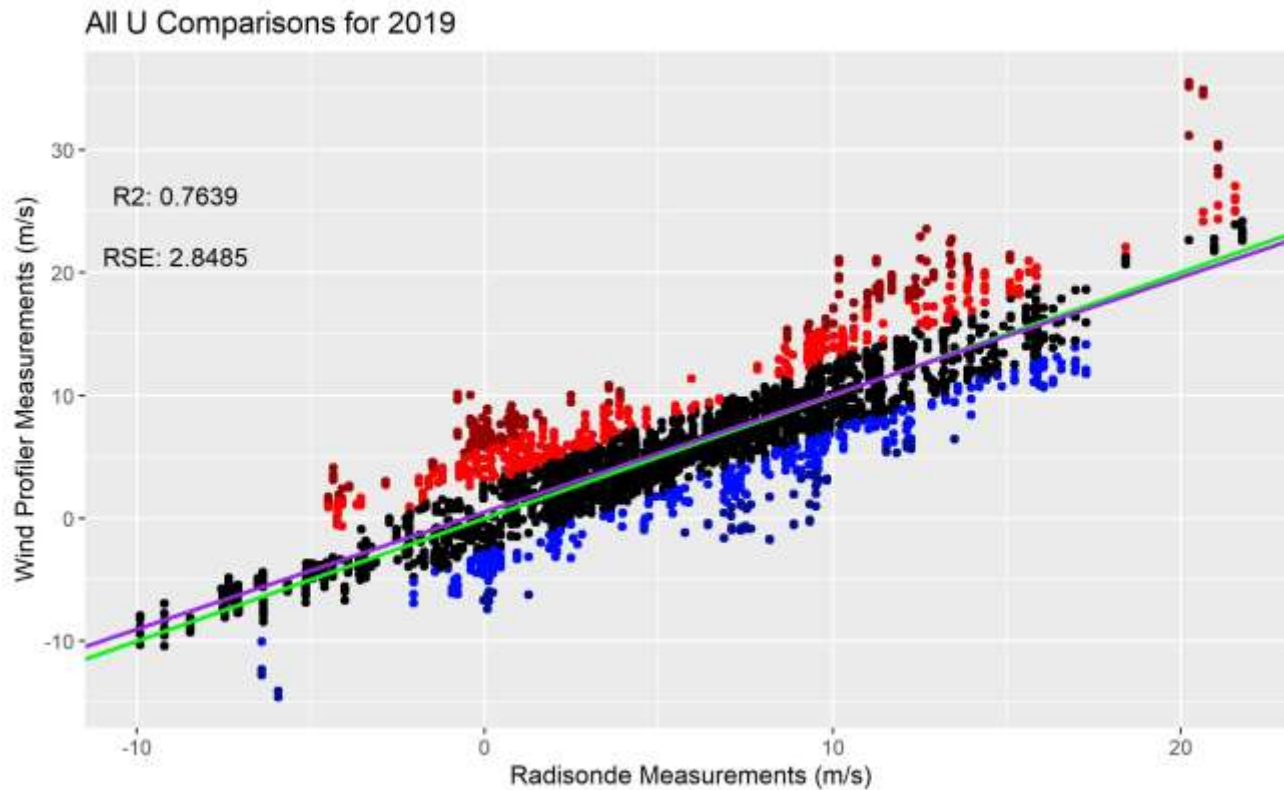
- *physics of detection; time of day; error characteristics*
- *BL physics (variability);*

Radars have more to offer that is not yet fully exploited.

WIND Profilers: Suggested work

Thanks Ricardo for the help

WIND Profilers Vs Sonde (*Intern: Henry Budris 2019**)



I have the data

- *Redo the analysis*
- *Compare single profiles with SNR etc*

WIND Profilers: Frequencies

Jun 9-12, 2015 case Plot SNR and compare with lidar data (Ozone, CL51)

Data in googledocs: can you plot the ceilometer and wind (speed/SNR) on single plot and discuss

